# SBE 16plus-IM SEACAT Reference Sheet

(see SBE 16plus-IM User's Manual for complete details)

### Sampling Modes

- **Polled** 16*plus*-IM takes one sample and transmits data.
- Autonomous At pre-programmed intervals, 16plus-IM wakes up, samples, stores data in FLASH memory, and powers off.
- **Combo** Last Autonomous sampling data is transmitted.

## Communication Setup Parameters

- 1. Double click on SeaTerm.exe.
- 2. Once main screen appears, in Configure menu select SBE 16plus. Click on COM Settings tab in dialog box. Input:
  - Serial Port: COM1 through COM10 are available
  - Baud Rate: 1200, 2400, 4800, or 9600
  - Data Bits: 8
  - Parity: No Parity

- Mode: Inductive Modem
- Modem/RS-485 ID:

Pre-deployment testing: Automatically get ID

Deployment with multiple SBE 16plus-IMs: Prompt ID

## Deployment

- 1. Install fresh batteries:
  - A. *Remove modem end cap*: Wipe dry housing/end cap seam. Remove 3 flat Phillips-head screws from end cap. Pull end cap out. Disconnect Molex connector connecting end cap to battery pack. Wipe O-ring mating surfaces in housing with lint-free cloth.
  - B. *Remove battery cover plate and batteries*: Remove 3 Phillips-head screws and washers from battery cover plate; remove cover plate. Turn 16*plus*-IM over and remove batteries.
  - C. Reinstall batteries, cover plate, and end cap: Install new batteries, with + terminals against flat battery contacts and terminals against spring contacts. Reinstall battery cover plate and 3 screws/washers. Remove water from O-rings and mating surfaces with lint-free cloth. Inspect O-rings and mating surfaces for dirt, nicks, and cuts. Clean as necessary. Apply light coat of O-ring lubricant to O-ring and mating surfaces. Plug Molex connector together. Fit end cap into housing. Reinstall 3 Phillips-head screws to secure.
- 2. Attach 16plus-IM to insulated mooring cable with Sea-Bird mounting brackets. Install (optional) ICC on mooring cable.
- 3. SIM wiring and configuration:
  - A. Power Normal Setting: Power common to JP1 pin 1, 7-25 VDC to JP1 pin 2, jumper on J3.
  - B. *Interface* Connect I/O cable to JP2 and to computer serial port. RS-232: J1 pins 2 and 3, J2 pins 2 and 3, J4 no jumper.

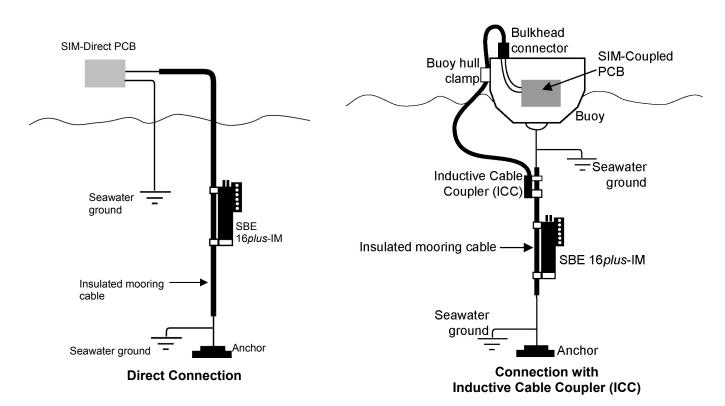
RS-485: J1 pins 1 and 2, J2 pins 1 and 2, J4 jumper.

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C. *Inductive Cable Connection* – With ICC: Connect ICC to JP4;

D. Deployed Operation – Jumper J5

Without ICC: Connect mooring cable and seawater ground to JP4. *Instrument Setup and Lab Testing* – No jumper on J5.



### **Command Instructions and List**

- Input commands in upper or lower case letters and register commands by pressing Enter key.
- 16plus-IM sends ?CMD if invalid command is entered.
- If system does not return S> prompt after executing a command, press Enter key to get S> prompt.
- If new command is not received within 2 minutes after completion of a command, 16plus-IM communications microcontroller returns to quiescent (sleep) state.
- If in quiescent (sleep) state, re-establish communications by clicking Connect on Toolbar or entering **PWRON** command to get S>.

Shown below are the commands used most commonly in the field. See the Manual for complete listing and detailed descriptions.

FUNCTION	CATEGORY	COMMAND	DESCRIPTION
SIM Commands	e.rragoni	PWRON	Send wakeup tone to all 16plus-IMs.
		PWROFF	Send power off command to <b>all</b> 16 <i>plus</i> -IMs. Logging and memory unaffected.
		DS	Display SIM firmware version and setup parameters.
	-	BAUD=x	x= baud from SIM to computer (1200, 2400, 4800, or 9600). Default 9600.
		DATANNMAX=x	x= timeout that applies to <b>DATAii</b> ; default 1000 milliseconds.
		RELAYMAX=x	x= timeout that applies to DATAII, detault 1000 infiniseconds.  x= timeout that applies to all other commands; default 20 seconds.
			Echo characters received from computer.  Do not.
		ECHOON ECHOOFF	x=Y (default): Send PWRON to 16 <i>plus</i> -IMs when power applied to SIM.
		AUTOPWRON=x	x=N: Do not send <b>PWRON</b> .
16 <i>plus-</i> IM Communication Microcontroller Commands	Global		Command <b>all</b> 16 <i>plus</i> -IM communication microcontrollers to get data from
		GDATA	16 <i>plus</i> -IM acquisition microcontrollers. Communication microcontrollers hold data
			in buffer until receiving <b>DATAii</b> .
		MMDDYY=mmddyy	Set all real-time clocks: month, day, year. Must follow with HHMMSS=.
		DDMMYY=ddmmyy	Set all real-time clocks: day, month, year. Must follow with HHMMSS=.
		HHMMSS=hhmmss	Set all real-time clocks: hour, minute, second.
	Get Data	DATAii	Get data obtained with GDATA from 16plus-IM with ID=ii.
	16plus-IM	ID?	Display 16plus-IM ID (ID = ii, where ii=0 to 99)
	ID	*ID=ii	Set ID to ii (ii=0 to 99). Only one 16plus-IM can be on line or all 16plus-IMs on line
	Firmware	!iiDS	will have same ID. Computer responds by requesting verification.
		#iiDS	Display communication microcontroller firmware version.
	Status		Display status and setup parameters.
	General Setup	#iiMMDDYY=mmddyy	Set real-time clock month, day, year. Must follow with #iiHHMMSS=.
		#iiDDMMYY=ddmmyy	Set real-time clock day, month, year. Must follow with #iiHHMMSS=.  Set real-time clock hour, minute, second.
		#iiHHMMSS=hhmmss	
		#iiMOOREDPUMPMODE=x	x=0: No pump. x=1: Run pump for 0.5 seconds before each sample. x=2: Run pump during each sample.
		#iiNCYCLES=x	x= number of samples to take and average every #iiSAMPLEINTERVAL seconds.
		#IINCTCLES-X	After uploading all data, send this command before starting to log to make entire
		#iiINITLOGGING	memory available for recording. If not sent, data stored after last sample.
			x=0: No pressure sensor. x=1: Strain gauge pressure sensor.
	Pressure	#iiPTYPE=x	x=3: Quartz pressure sensor with temperature compensation.
	Sensor Setup	#iiREFPRESS=x	x= reference pressure (decibars) (for 16 <i>plus</i> -IM without pressure sensor).
	Voltage Sensor Setup	#iiVOLT0=x #iiVOLT1=x	<b>x=Y</b> : Enable external voltage (voltage 0, 1, 2, or 3).
		#iiVOLT2=x #iiVOLT3=x	<b>x=N</b> : Do not.
			x= time (seconds) to wait after switching on external voltage before sampling
		#iiDELAYBEFORESAMPLING=x	(0-32,000 seconds). Default 0 seconds.
		#iiBIOWIPER=x	x=Y: Configuration includes ECO-FL fluorometer with Bio-Wiper. x=N: Does not.
	RS-232 Setup	#iiSBE38=x	<b>x=Y</b> : Enable SBE 38 secondary temperature sensor. <b>x=N</b> : Do not.
	<u> </u>	#iiOUTPUTFORMAT=x	x=0: output raw data in Hex. $x=1$ : output converted data in Hex.
	Output Format Setup	#IIOUTFUTFORWIAT=X	x=2: output raw data in decimal. x=3: output converted data in decimal.
		#iiOUTPUTSAL=x	x=Y: Calculate salinity (psu) (if #iiOUTPUTFORMAT=3). x=N: Do not.
		#iiOUTPUTSV=x	x=Y: Calculate sound velocity (m/sec) (if #iiOUTPUTFORMAT=3). x=N: Do not.
		#iiOUTPUTSN=x	x=Y: Output sample number with data (if #iiOUTPUTFORMAT=3). x=N: Do not.
	l	#iiSAMPLEINTERVAL=x	$\mathbf{x}$ = interval between samples (10 - 14400 seconds).
		#iiSTARTNOW	Start logging now.
		#iiSTARTMMDDYY=mmddyy	Delayed logging start: month day year. Must follow with #iiSTARTHHMMSS=.
		#iiSTARTDDMMYY=ddmmyy	Delayed logging start: day month year. Must follow with #iiSTARTHHMMSS=.
		#iiSTARTHHMMSS=hhmmss	Delayed logging start: hour, minute, second.
		#iiSTARTLATER	Start logging at delayed start time. Data stored in FLASH memory.
		#iiSTOP	Stop logging or waiting to log. Must send this command before uploading data.
	Data Upload	#iiDDb,e	Upload data from scan <b>b</b> to <b>e</b> . Send <b>#iiSTOP</b> before sending this.
		#iiDHb,e	Upload headers from header <b>b</b> to <b>e</b> .
	Polled Sampling	#iiSL	Output last sample from buffer.
		#iiSLT	Output last sample from buffer, take new sample, and store in buffer.
		#iiTS	Take sample, store data in buffer, and output data.
		#iiTSSON	Take sample, store in buffer and FLASH memory, and output data.
	Coefficients	#iiDCAL	Display calibration coefficients.